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## Structural Behaviour of Steel Building with Modified X-Braced EBF (Eccentrically Braced Frames) by Pushover Analysis

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**Abstract**— In this paper, modified X-braced EBF steel frame is designed using pushover analysis. This study discussed five models of a steel building with 10 floors. The dimension of each model is 18 m width, 18 m length, and 4 m height. The building has a function as an office in Palembang. The building uses two types of EBF bracing, that is X with a vertical link and horizontal link. The result of the study shows that X bracing, with horizontal link model, has the best effectiveness to increase building stiffness and strength. Model 5 with X Bracing and horizontal link can reduce storey drift to 57.71 %, and drift ratio is 72.38%. By pushover analysis, this model gained the most effective performance point with base shear of 441.67 ton. The performance of the five building models is immediate occupancy (IO).

**Keywords**— pushover analysis; performance point; immediate occupancy

### I. INTRODUCTION

One of the systems that are used to decrease a risk of damage caused by an earthquake is the bracing system. Generally, the bracing system used in the steel structure. The design of steel structure has three types. They are moment resisting frame (MRF), concentrically braced frame (CBF), and eccentrically braced frame (EBF). EBF is a combination of two conventional bracing systems namely MRF and CBF. The characteristic of bracing EBF has link beam. The usage of EBF is to reduce the seismic load. Bracing EBF has bigger ductility compared to MRF and CBF, so that the energy dissipation capacity increased [1], [2], [3]. In EBF system, the usage of vertical link caused base shear decreased compared to horizontal link so that EBF has been found small displacement and energy dissipation increased [4], [5]. This paper discussed the response of steel structure to resist earthquake by pushover analysis. There are five models of a steel structure with ten floors using X bracing with a vertical link and horizontal link. The length of link beam is 1 m. The purpose of this study is to analyses plastic hinge distribution, to investigate the first plastic hinge formation, to determine the performance level of the building based on ATC-40, and to evaluate the effectiveness of the models to reduce seismic energy. The scope of the discussion in this study is seismic performance analysis by pushover analysis. The result is drift storey, drift ratio, capacity curve, performance level, and plastic hinge formations and propagation.

Pushover analysis can be used for indicating the damage of structures. Pushover analysis is a way of nonlinear static analysis by simplification of the time history nonlinear analysis [6], [7], [8]. Pushover analysis is done by applying an incremental load in a structure until a certain condition. The static load value increased gradually which caused the first yield. Pushover analysis identified the weakness in structure so that the structural element can be strengthened based on the weakness. Pushover analysis produced pushover curve which describes the correlation between shear and displacement. Pushover analysis also produced the comparison of performance level to structure [9], [10], [11]. The main steps of pushover analysis are [12], [13]:

- Determine point control to monitor the structure displacement
- Calculate capacity curve based on several kinds of lateral force distribution
- Estimation of lateral displacement
- Evaluate structure performance level with control point on target displacement based on ATC-40

As can be seen from Fig. 1, point B represent the yields a condition of the structure. From point B to point C showed the plastic deformation of the structure. Point C, D, and E represent the ultimate capacity, the residual strength, and total failure of structure from pushover analysis.

Point IO-immediate occupancy, LS-life safety, and CP-collapse prevention showed the acceptance criteria when hinge develops in the structure [3].

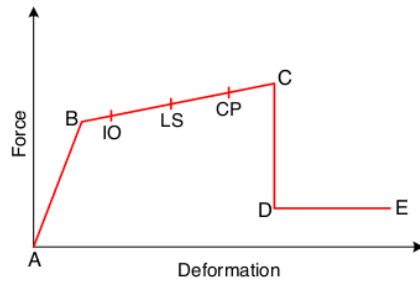


Fig. 1 Pushover curve (ATC-40)

## II. MATERIAL AND METHOD

In this study, two model of the frame to be analysed, e.g., moment resisting frame (Model 1), and four eccentrically braced frame (Model 2, Model 3 and Model 4).

Steel sections used in this study are shown in Table 1. The mechanical properties of steel sections with the yield strength 340MPa and E 200,000MPa.

The plan of the building can be seen in Fig. 2, and the thick line (red line) showed the position of the bracing. The span of the beam is 6 m, and the floor height is 4 m, and the building consisted of 10 floors. Fig. 3 showed the five models to be studied.

TABLE I  
STEEL SECTIONS USED

Storey	Column Section	Beam Section	Diagonal Bracing	Vertical and Horizontal Bracing
10	W10x100	W16x40	W8x31	W8x48
9	W10x100	W16x40	W8x31	W8x48
8	W10x100	W16x40	W8x31	W8x48
7	W12x120	W16x40	W8x31	W8x48
6	W12x120	W16x40	W8x31	W8x48
5	W12x120	W16x50	W8x31	W8x48
4	W14x176	W16x50	W8x31	W8x48
3	W14x176	W16x50	W8x31	W8x48
2	W14x176	W16x50	W8x31	W8x48
1	W14x370	W16x50	W8x31	W8x48

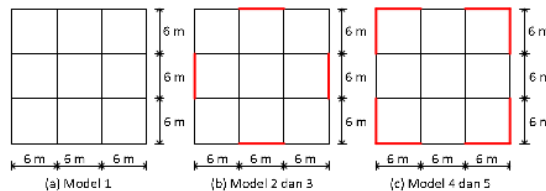


Fig. 2 Building plans

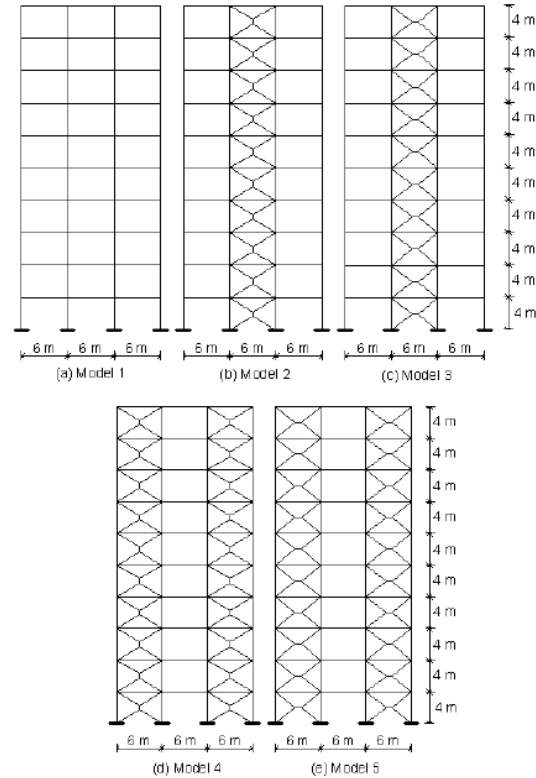


Fig. 3 Structure models

## III. RESULTS AND DISCUSSION

### A. Building's Mass and Base Shear

The ground motion generates internal forces caused by the building mass vibration. The comparison of building's mass of each model is shown in Table 2 and Fig. 4.

TABLE II  
COMPARISON OF BUILDING'S MASS

Storey	Building's mass (ton)				
	Model 1	Model 2	Model 3	Model 4	Model 5
10	136.81	138.19	137.40	139.57	137.99
9	235.96	238.73	237.14	241.49	238.33
8	235.96	238.73	237.14	241.49	238.33
7	236.84	239.61	238.03	242.38	239.21
6	237.80	240.57	238.98	243.33	240.17
5	239.80	242.57	240.99	245.33	242.17
4	242.35	245.12	243.54	247.88	244.72
3	245.03	247.79	246.21	250.56	247.39
2	245.03	247.79	246.21	250.56	247.39
1	254.22	257.75	255.40	261.28	256.59
$\Sigma$	<b>2,309.85</b>	<b>2,336.88</b>	<b>2,321.09</b>	<b>2,363.91</b>	<b>2,332.33</b>

The base of a structure is considered to be the level where the ground motions are imparted into the structure. Base shear is an estimate of the maximum expected lateral force that will occur due to seismic ground motion at the base of a structure. Base shear ( $V$ ) is a function of buildings mass. The comparison of base shear of each model is shown in Table 3 and Fig. 5(a) and 5(b).

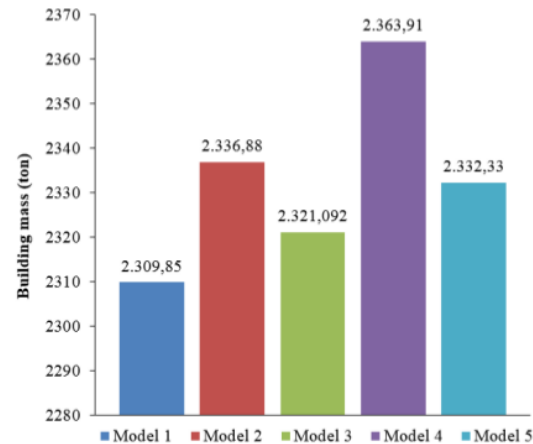


Fig. 4 Comparison of building's mass

TABLE III  
COMPARISON OF BASE SHEAR

Model	Scale Factor (g.I/R)		Base Shear (ton)	
	x-direction	y-direction	$V_x$	$V_y$
Model 1	1.226	1.226	39.138	33.595
Model 2	1.226	1.226	49.508	44.290
Model 3	1.226	1.226	53.479	51.103
Model 4	1.226	1.226	57.865	52.370
Model 5	1.226	1.226	65.510	63.629

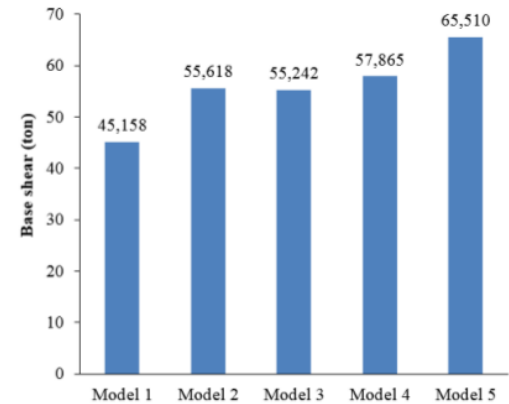


Fig. 5(a) Comparison of base shear  $V_x$

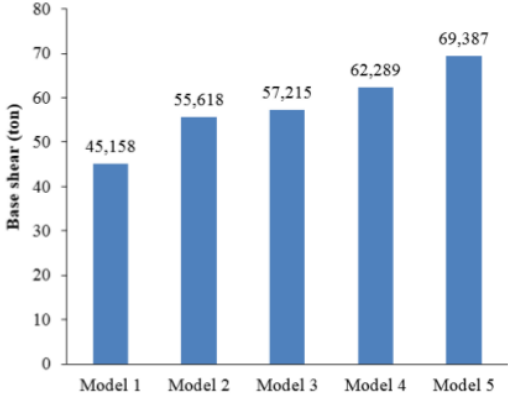


Fig. 5(b) Comparison of base shear  $V_y$

### B. Lateral Displacement

The comparison of floor horizontal deflection in x and y directions of each model is shown in Table 4. Based on the analysis results, it can be seen that model 5 with X EBF bracing is the most effective bracing system to reduce horizontal deflection. Model 5 with the horizontal link is capable of reducing deflection to 48.22% on x-direction and 57.71% on y-direction. Graphs of lateral displacements in x and y-direction can be seen in Fig. 6(a) and Fig. 6(b).

TABLE IV  
THE COMPARISON OF LATERAL DISPLACEMENT

Model	$\Delta_{maks}$ (mm)		Percentage of lateral displacement reduction to model 1	
	x-direction	y-direction	x-direction	y-direction
1	39.403	55.107	0	0
2	28.672	37.362	27.23%	32.20%
3	25.056	29.446	36.41%	46.57%
4	22.910	30.823	41.86%	44.07%
5	20.360	23.286	48.22%	57.71%

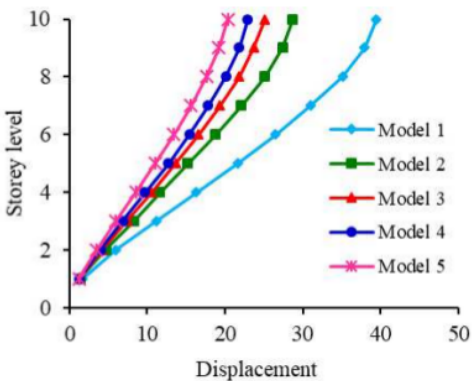


Fig. 6(a) Lateral displacement in x direction (mm)

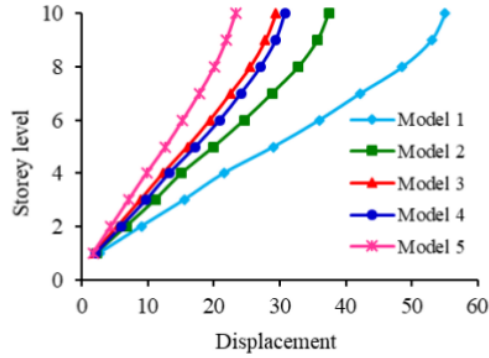


Fig. 6(b) Lateral displacement in y-direction (mm)

### C. Drift Ratio

Floor horizontal displacements of each model are shown in Table 5 and 6. Drift ratio of each model are shown in Table 7 and Table 8 and also in Fig. 7(a) and (b).

TABLE V  
FLOOR DISPLACEMENT (X DIRECTION)

Storey	$\delta_x$ (mm)				
	Model 1	Model 2	Model 3	Model 4	Model 5
10	39.403	28.672	25.056	22.910	20.360
9	37.949	27.364	23.748	21.784	19.179
8	35.108	25.134	21.814	20.078	17.571
7	30.980	22.081	19.334	17.844	15.581
6	26.519	18.752	16.596	15.389	13.368
5	21.604	15.250	13.618	12.670	10.977
4	16.278	11.636	10.455	9.739	8.469
3	11.203	8.251	7.357	6.913	5.993
2	6.024	4.705	4.181	3.986	3.488
1	1.680	1.444	1.324	1.278	1.185

TABLE VI  
FLOOR DISPLACEMENT (Y DIRECTION)

Storey	$\delta_y$ (mm)				
	Model 1	Model 2	Model 3	Model 4	Model 5
10	55.107	37.362	29.446	30.823	23.286
9	53.022	35.712	27.805	29.385	21.910
8	48.568	32.779	25.466	27.110	20.068
7	42.185	28.780	22.546	24.112	17.823
6	36.023	24.579	19.394	20.871	15.340
5	29.114	20.005	15.967	17.231	12.656
4	21.532	15.107	12.319	13.238	9.838
3	15.499	11.078	8.947	9.698	7.132
2	8.973	6.692	5.415	5.919	4.373
1	2.724	2.243	1.938	2.103	1.677

Drift ratio is reduced significantly if bracing is used on the steel building. At the fifth floor of model 2, drift ratio is

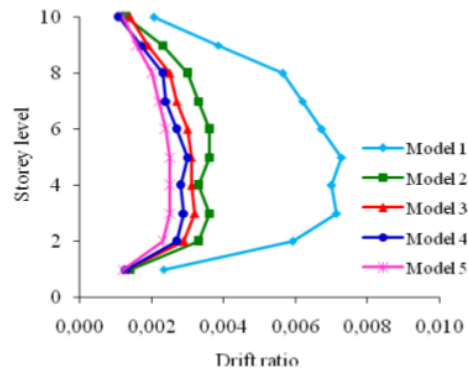
reduced 50.69% for x-direction and 55.33% for y-direction. At the fifth floor of model 3, drift ratio is reduced 57.53% for x-direction and 64.76% for y-direction. At the fifth floor of model 4, drift ratio is reduced 58.90% for x-direction and 61.91% for y-direction. At the fifth floor of model 5, drift ratio is reduced 65.75% for x-direction and 72.38% for y-direction.

TABLE VII  
DRIFT RATIO (X-DIRECTION)

Storey	DRIFT RATIO				
	Model 1	Model 2	Model 3	Model 4	Model 5
10	0.0020	0.0013	0.0013	0.0011	0.0012
9	0.0039	0.0022	0.0019	0.0017	0.0016
8	0.0057	0.0031	0.0025	0.0023	0.0020
7	0.0061	0.0033	0.0027	0.0025	0.0022
6	0.0068	0.0035	0.0030	0.0027	0.0024
5	0.0073	0.0036	0.0032	0.0029	0.0025
4	0.0070	0.0034	0.0031	0.0028	0.0025
3	0.0071	0.0035	0.0032	0.0029	0.0025
2	0.0060	0.0033	0.0029	0.0027	0.0023
1	0.0023	0.0014	0.0013	0.0013	0.0012

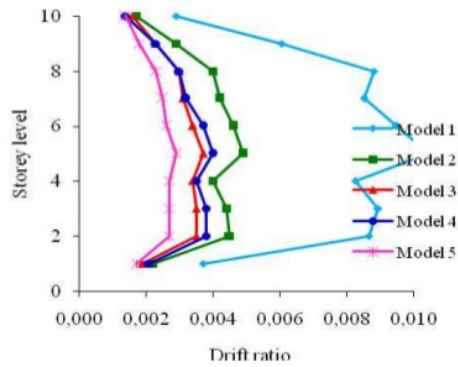
TABLE VIII  
DRIFT RATIO (Y-DIRECTION)

Storey	DRIFT RATIO				
	Model 1	Model 2	Model 3	Model 4	Model 5
10	0.0029	0.0016	0.0016	0.0014	0.0014
9	0.0061	0.0029	0.0023	0.0023	0.0018
8	0.0088	0.0040	0.0029	0.0030	0.0022
7	0.0085	0.0042	0.0032	0.0032	0.0025
6	0.0095	0.0046	0.0034	0.0036	0.0027
5	0.0104	0.0049	0.0036	0.0040	0.0028
4	0.0083	0.0040	0.0034	0.0035	0.0027
3	0.0090	0.0044	0.0035	0.0038	0.0028
2	0.0029	0.0016	0.0016	0.0014	0.0014
1	0.0061	0.0029	0.0023	0.0023	0.0018



(a) x-direction





(b) y-direction

Fig. 7 Drift ratio

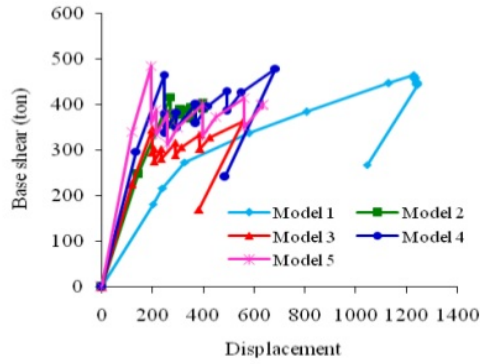
#### D. Performance Point and Performance Level

Base shear forces and its corresponding displacements for each model are shown in Table 9, Fig. 8(a), and 8(b). Performance point is a correlation between base shear and displacement. Curve capacity and performance points of the five model can be seen in Fig. 9(a) and 9(b).

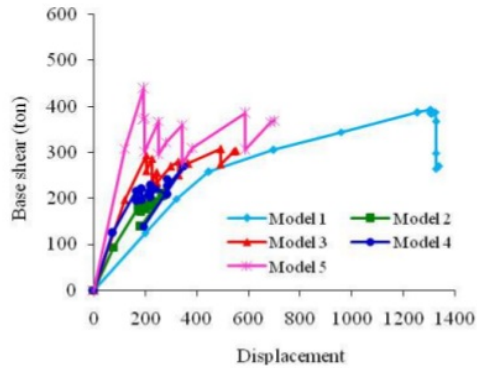
The best performance point is shown by model 5 for x or y-direction. In model 5 x direction shear force limit increased 72.33% and displacement decreased 43.34%, while for y-direction shear force limit increased 84.07%, and displacement decreased 52.63%. In model 4 for x-direction, shear force limit increased 53.67%, and displacement decreased 34.07%, while for y-direction shear force limit increased 7.82% and displacement decreased 47.39%. In model 3 for x-direction, shear force limit increased 30.55%, and displacement decreased 33.57%, while for y-direction, shear force limit increased 23.01% and displacement decreased 21.53%. In model 2 for x-direction, shear force limit increased 38.84%, and displacement decreased 25.00%, while for y-direction shear force limit increased 6.88% and displacement decreased 32.39%. The performance level of each model is described in Table 10.

TABLE IX  
BASE SHEAR FORCE AND DISPLACEMENT

Model	Base Shear (ton)	Displacement (mm)	Base Shear (ton)	Displacement (mm)
	x-direction		y-direction	
1	256.30	299.10	222.59	372.11
2	355.85	224.31	207.28	251.60
3	334.60	198.69	273.80	292.00
4	393.85	197.21	205.19	195.76
5	441.67	169.48	409.73	176.27

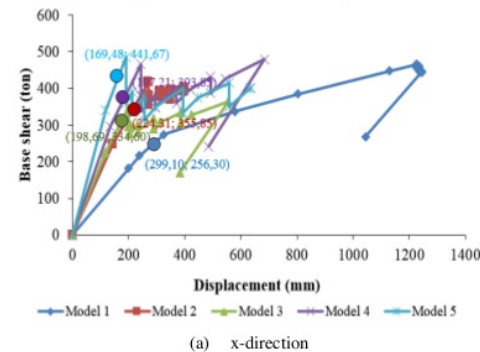


(a) x-direction

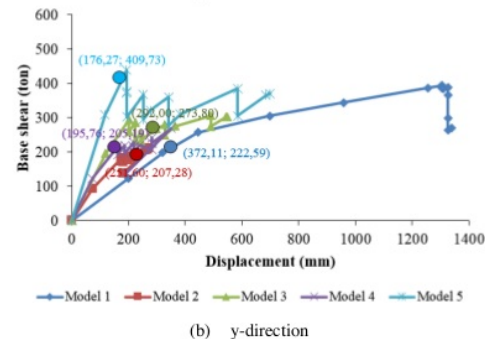


(b) direction

Fig. 8 Base shear force and displacement



(a) x-direction



(b) y-direction

Fig. 9 Curve capacity and performance point

TABLE X  
PERFORMANCE LEVEL

Model	Maximum total drift	Maximum inelastic drift	Maximum total drift	Maximum inelastic drift	Performance level
	x-direction		y-direction		
1	0.0075	0.0025	0.0093	0.0043	IO
2	0.0056	0.0020	0.0063	0.0044	IO
3	0.0050	0.0020	0.0073	0.0043	IO
4	0.0049	0.0016	0.0049	0.0031	IO
5	0.0042	0.0013	0.0044	0.0015	IO

#### E. Plastic Hinge Propagation

The beam section deformation where the plastic bending occurs is described as a plastic hinge. Propagation path of the plastic hinges of the 5 models in x-direction was shown in Fig. 10. Propagation path of the plastic hinges of the 5 models were y-direction in shown in Fig. 11.

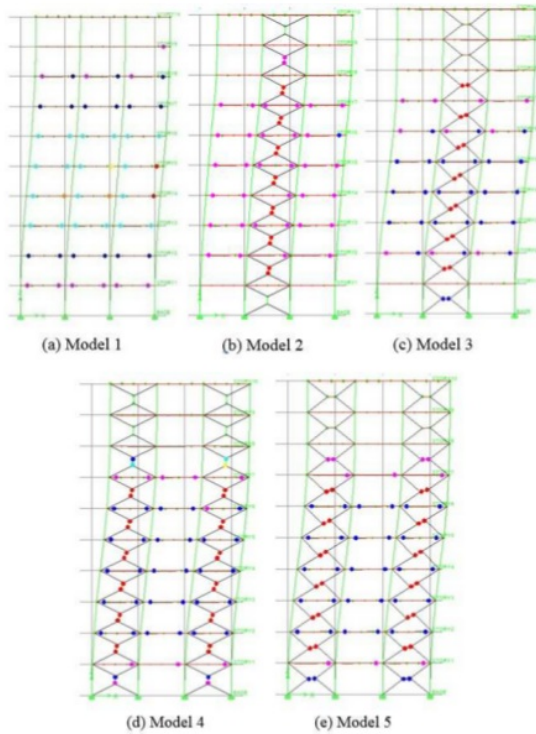


Fig. 10 Plastic hinge propagation in x-direction in step 15

Plastic hinge propagation mechanism of model 1 is shown in Fig. 10(a) dan 11(a). In x-direction, plastic hinge occurred in 15<sup>th</sup> steps with base shear 268.31 ton, displacement 1.044 mm. There are two red beams which indicate collapse condition. In y-direction, plastic hinge also occurred in steps 15 with base shear 269.24 ton, displacement 1.338 mm. There are six beams collapsed.

The plastic hinge mechanism of model 2 is shown in Fig. 8(b) and 9(b). In x-direction, the plastic hinge occurs in 15th step with base shear 393.13 ton, displacement 399.43 mm. There are two red beams which indicate collapse condition.

In y-direction, plastic hinge also occurred in steps 15 with base shear 137.65 ton, displacement 182.07 mm. There are six beams collapsed. In step 15, some bracing collapsed, while other beams were in the first yielding.

The plastic hinge mechanism of model 3 is shown in Fig. 8(c) and 9(c). In x-direction, the plastic hinge occurs in 15th step with base shear 169.70 ton, displacement 382.18 mm, some bracing has collapsed, and beams come into IO level. In y-direction, the plastic hinge also occurs in steps 15 with base shear 303.54 ton, displacement 549.11 mm, some bracing has collapsed, and beams come into IO level.

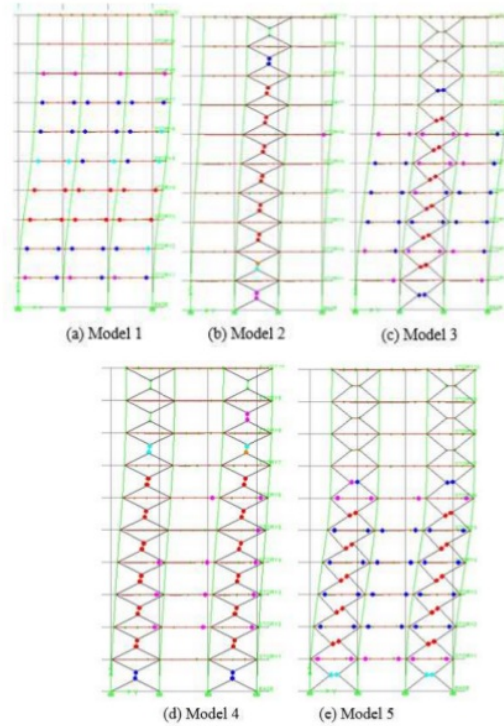


Fig. 11 Plastic hinge propagation in y-direction in step 15

The plastic hinge mechanism of model 4 is shown in Fig. 8(d) and 9(d). In x-direction, the plastic hinge occurs in 15th step with base shear 241.48 ton, displacement 484.74 mm, some bracing has collapsed, and beams come into IO level. In y-direction, the plastic hinge also occurs in steps 15 with base shear 139.39 ton, displacement 192.08 mm, some bracing has collapsed, and beams come into IO level.

The plastic hinge mechanism of model 5 is shown in Fig. 8(e) and 9(e). In x-direction, the plastic hinge occurs in 15th step with base shear 401.31 ton, displacement 636.22 mm, some bracing has collapsed, and beams come into IO level. In y-direction, plastic hinge is also occurred in steps 15 with base shear 370.17 ton, displacement 698.34 mm, some bracing has collapsed, and beams come into IO level.

#### IV. CONCLUSION

The study of structural response and pushover analysis caused by the earthquake in five models concludes the followings: Floor horizontal displacement in model 5

reduced to 57.71%; The use of bracing model 5 reduced structural response by 72.38%; Performance point of model 5 showed increase in shear force to 84.07% and a decrease in displacement to 52.63%. In this study, the performance level of the five building models is in immediate occupancy (IO).

The sequence of plastic hinge propagation is in accordance with the concept of the strong column weak beam. Plastic hinge formation didn't occur in the columns.

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