

# book chapter

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# Green Machining of Thin-Wall Titanium Alloy



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28  
54 **Abstract** Titanium and its alloys are well known as difficult-to-machine materials due to low thermal conductivity and chemical adherent to cutting tools. Ti6Al4V is most widely used in a thin-wall structure application in the field of aerospace industry. Thin-wall machining encounters vibration and that furthermore increases fluctuations in cutting force. Select the type of machining process that generates sustainability in thin-wall machining is crucial to master. One of the innovations in conventional machining is to promote vegetable oils as the cutting fluids. These cutting fluids offer environmentally friendly cooling as well as lubrication to foster the cleaner production in the aerospace industry. Hence, the capable, sustainable cutting fluid has to be a future of the machining process. Minimum quantity lubrication (MQL) using coconut oil is recognised to be the green machining technique in milling titanium alloy. Coconut oils as nanofluids are attracting considerable attention due to good lubrication properties, non-toxic and biodegradable nature, and easy recycling. Therefore, it is a significant finding to observe the stability, dynamic behaviour, surface quality, and environmental aspects of cutting fluids in milling thin-walled Ti6Al4V. The findings reported in this chapter show

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21 that the use of coconut oil in the MQL system for thin-wall machining of Ti6Al4V  
22 is a promising innovation in the future of aerospace industries. At last, this chapter  
23 also sheds light on the treatment of exhausted cutting fluids.

24 **Keywords** Thin wall · Titanium alloy · Vibration · Surface quality  
25 MQL · Nanofluids · Sustainable cutting fluids

## 27 1 Introduction

28 Cooling and lubrication are prime requirements in any machining process; there-  
29 fore, cutting fluids play a pivotal role in machining. Cutting fluids cool, lubricate  
30 and thereby reduce the friction and heat generated in the machining zone. Even  
31 though cutting fluids have a reasonably low cost, their handling and carrying costs  
32 are very high, and their toxic nature and disposal are challenging [1]. It compels  
33 to choose the type of processes that are sustainable i.e., productive, clean, and  
34 green.

35 The primary means to control the tool wear propagations are to master the  
36 lubrication and heat removal rate in the machining process. One of them is the use  
37 of flood-cooling system. Although this system was proven at lower cutting speed, a  
38 decreasing performance occurs at higher cutting speeds. This phenomenon is  
39 caused by the high amount of heat generated in the critical areas (tool–workpiece  
40 interface), which cannot be reached by the cutting fluids; hence, the interface cannot  
41 be cooled. Ecological hazards, carbon cycle, operator’s health issues, and mineral  
42 oils rising cost have brought the utilisation of vegetable oils [2].

43 This limitation led to the use of MQL and cryogenic system in machining. The  
44 use of MQL, which required the gasification of oil mist, can absorb heat in the  
45 cutting area effectively. Another advantage of MQL is economical costs and an  
46 environmentally friendly technology. Nowadays, many researchers are trending to  
47 shift to use the vegetable oils as the cutting fluids. It possesses a higher boiling  
48 point, higher flash point, and excellent lubricity properties, hence lesser loss in the  
49 oil mist [2].

50 Initially, almost all of the research regarding machining on Ti6Al4V all this time  
51 were focused on high-speed machining, which followed by the technique, that  
52 enables the applying of the dry-cutting condition. Furthermore, the development of  
53 machining on Ti6Al4V leads to the utilising of vegetable oils as cutting fluids,  
54 mainly palm oil. Unfortunately, the abundance of palm oil could not cover the fact  
55 that palm oil contains at least 50% unsaturated fatty acid [3]. The limitation of this  
56 property affected the palm oil tends to be oxidative. The result of conventional  
57 machining on Ti6Al4V indicated the use of vegetable oil suitable for low and  
58 medium speed [4–6].

59 Current studies in thin-wall machining are focused on the use of finite element  
60 method (FEM). This approach was utilised in the analysing of stress distribution,  
61 deformation, mechanical vibration, geometric accuracy, and surface quality [7–10].





33  
62 The important factors such as variable cutting force, tool deflection, and machining  
63 stability are not taken into account in the existing FEM models. There is a lack of  
64 information concerning the thin-wall machining of Ti6Al4V using vegetable-based  
65 nanofluids as a lubricant and the treatment of wasted cutting fluids. Therefore, it is  
66 essential to evaluate the performance of thin-wall machining on Ti6Al4V under  
67 MQL using coconut oils as nanocutting fluids and the potential treatment of wasted  
68 cutting fluid before it delivered to the environment.

15  
69 Thin-walled structures are common useful part of modern aircraft, such as the  
70 integral panel, framework shells, and thin-walled membranes to improve the  
71 equipment performance by designers [11]. Thin wall is defined by [12] to mean a  
72 typical machining process that forms a piece of specific height-depth ratio  
73 approximately 15:1 and wall thickness approximately 3–5 mm. Ti6Al4V is the  
74 most widely used titanium alloy in thin-wall design requirements.

5  
75 Titanium materials have received much attention due to superior corrosion  
76 resistance and mechanical properties such as high strength, light weight, high wear,  
77 fatigue strength, tensile strength, and wear resistance. Hence, these materials are  
78 recommended for use in the aerospace and automotive industries. Titanium alloy  
79 also has much applications in the field of energy, biomedical, shipping, chemical  
80 vessel, turbines, and electrochemical industries because of its higher structural  
81 efficiency characteristics [13, 14]. However, the high temperature strength com-  
82 bined with the low thermal conductivity contributes to the poor machinability [15].  
83 Thus, the Ti6Al4V is well known a typical difficult-to-cut material. This problem  
84 caused difficulties in dissipating the generated heat in the contact zone. It leads to  
85 the very high temperature condition, which occurs in the tool tip and severely  
86 impairs their machinability [14].

4  
87 The first description and evidence of chatter were performed in 1907 by Taylor  
88 [16]. However, the regenerative chatter theory reported by Tobias at the 1950s is  
89 the first systematic study in this field [14]. Researchers explained regenerative  
90 chatter in orthogonal cutting and developed a stability lobe theory for a  
91 two-dimensional case in the 1960s. A new analytical form of the stability lobe  
92 theory for milling presented in the middle of 1990s. More recently, some research  
93 obtaining the stability lobe diagram of a chatter system with consideration of the  
94 change of cutting position and the changes of workpiece mass and stiffness during  
95 milling process [17]. For example, [16] obtaining the stability lobes method.  
26  
96 Thus a three-dimensional lobe diagram has been developed base on the relative  
97 movement of systems.

22  
98 Low heat conductivity [18] reduced rigidity [11] and complex structure [17] of  
99 thin-walled titanium alloy parts are the primary cause of unwanted vibration during  
100 the machining process. The limitation in high-speed thin-wall milling of titanium  
101 alloy is caused mainly by occurring of robust regenerative vibration known as  
102 chatter. The chatter is the leading cause of the machining process instability, tool  
103 wear, and inferior surface finish in the vertical milling of thin-walled Ti6Al4V [14].  
104 Conventionally, the cutting speeds in machining of titanium alloys are often limited  
105 to 60 m/min. Thus, it also gives rise to enormously increasing machining cost [14].  
106 Cost efficiency, sustainability, high productivity, and product quality are the major





107 focusing factors in manufacturing industry these days. To fulfil the aforementioned,  
108 machining operations should have high material removal rate, energy, and resource  
109 efficient, tighter surface tolerances [19].

110 A central problem<sup>4</sup> limitation which prohibits obtaining high productivity and  
111 quality of workpiece is the chatter effect which leads to the chatter marks on the  
112 surface, and such a result may be a prominent issue for high-speed and  
113 high-precision milling processes [17]. The surface topography indicated by [14] has  
114 an association with cutting vibrations<sup>14</sup>. The flexibility of workpiece and system tool  
115 was investigated by [16], under the action of the cutting forces that produce a  
116 vibration, giving rise to an irregular surface or wavy. The cutting force signals in  
117 thin-wall milling analysed using Fast Fourier Transform (FFT) was reported by [14]  
118<sup>15</sup> detecting chatter phenomenon. The theoretical chatter model proposed by [11]  
119 taking the stiffness characteristics of tool and workpiece into consideration aiming  
120 at the titanium thin-walled parts. The prediction seems<sup>11</sup> be a useful approach.  
121 Another research was carried out by [18], which propose to study the influence of  
122 the tool entering angle on the stability of the process and tool life based on cutting  
123 force in milling Ti6Al4V.

124 Many machining technologies have been focused on reducing the cutting zone  
125 temperature, in order to improve the machinability of the materials. In industrial  
126 practise, the cutting speed used to machine these difficult-to-cut materials is  
127 insufficient. Mainly, MQL and cryogenic machining have been employed to  
128 enhance the machinability of the materials through providing lubricity and sup-  
129 pressing high heat generation on the cutting surface during machining process of  
130 hard-to-cut materials, respectively [13].

131 The sufficient cooling system<sup>30</sup> for controlling the cutting temperature in  
132 machining is significant for the tool life improvement, especially when dealing with  
133 titanium alloys that have low thermal conductivity [13]. The recent development of  
134 eliminating both environmental hazards and machining cost has led to the usage of  
135 Minimum Quantity Lubrication (MQL). In this chapter, MQL is used to refer to a  
136 minuscule amount of lubricant spray (2 up to 50 mL/h) in a mist directly near  
137 tool-chip and/or tool-workpiece contact zone to provide the necessary lubricity,  
138 which is lacking in dry as well as wet machining. This technique is sometimes  
139 known as a near dry lubricating [20]. The use of MQL conducts the gasification of  
140 oil mist, which could absorb the generated heat in the cutting<sup>29</sup> area. Another  
141 excellence of MQL is ecological friendly and more economy. It was reported that  
142 management of cutting fluid or coolant costs at least 16% of the product cost [21].  
143 MQL and cryogenic are classified as green machining techniques.

144 The machining performance was investigated by [13] using a variety of cooling  
145 systems such as flood cooling, MQL, and cryogenic. The investigation was per-  
146 formed using solid end mill on titanium alloy, Ti6Al4V. At the same trials, the  
147 cutting force was analysed through the tool breakage detection. Nevertheless, they  
148 found that the cutting force for MQL hBN 70 + cryogenic is higher compared to  
149 MQL hBN 70 which are 1011 and 865 N, respectively.

150 Another observation conducted by [15],<sup>25</sup> reported that cutting force increases  
151 when high cutting temperatures occur. Thus results in tool life reduction and poor



152 surface quality. Increase in MQL flow rate can reduce the cutting force and tool  
153 wear up to a certain extent only. It was found that machining with cryogenic  
154 conditions resulted in excessive tool wear and microfracture and increased the  
155 cutting forces. Cutting force increased significantly as the Ti-alloy hardens with the  
156 application of the liquid nitrogen during the cutting. The cutting force for MQL  
157 rapeseed oil and MQL + cryogenic are the same about 1000 N at 47.7 m/min and  
158 the cutting force at 76.4 m/min for MQL + cryogenic slightly lower than MQL.  
159 A paper reviewed by [21] in 2017 that MQL + SCCO<sub>2</sub> is not adequate for cutting  
160 force reduction. More concern reported by [15] when conducted deep hole drilling  
161 of Ti6Al4V. In this process, the cutting tool can be suffered from strong  
162 adhesion due to the lack of lubrication, when only cryogenic cooling employed. He  
163 concludes that the lubrication method such as MQL should be added for a better result  
164 in deep axial depth-of-cut machining.

165 Nowadays, many researchers have shifted to MQL using vegetable cutting  
166 fluids. Ecological hazards, operator's health, and mineral oils rising cost are  
167 important concerns where that vegetable oils can compete with mineral oils.  
168 Significant disadvantages of mineral oils are toxic, non-biodegradable, open carbon  
169 cycle, and non-renewable. Vegetable oils have a higher capacity to absorb pressure  
170 thus have good lubricity properties. They also have a higher flash point, better  
171 boiling point, and as a result, there is less loss from oxidizing. Coconut oil has been  
172 used for machining AISI 304. The result shows that coconut oil improved the  
173 surface finish, reduced tool wear compared to mineral oil [22].

174 It has been proved that flood cooling, though very useful at lower cutting speed,  
175 gets ineffective at higher speeds. This problem caused by the amount of heat  
176 generation at the tool-workpiece interface, which cannot be reached by the cutting  
177 fluids; hence the interface cannot be cooled [15, 23]. The result from green tech-  
178 niques of milling Ti6Al4V the power consumption of MQL is lowest followed  
179 by dry, cryogenic, laser-assisted machining, and wet machining [21].

180 During thin-wall milling of titanium alloy Ti6Al4V, the low rigidity can cause  
181 vibration. The phenomenon of the vibration is known as a chatter. When the rigidity  
182 of the thin-walled workpiece is far lower than the machine-tool system in the  
183 direction perpendicular to the machined surface, dynamic milling model of the  
184 thinly walled workpiece can be regarded as a 1° freedom system, as shown in Fig. 1  
185 [8, 14].

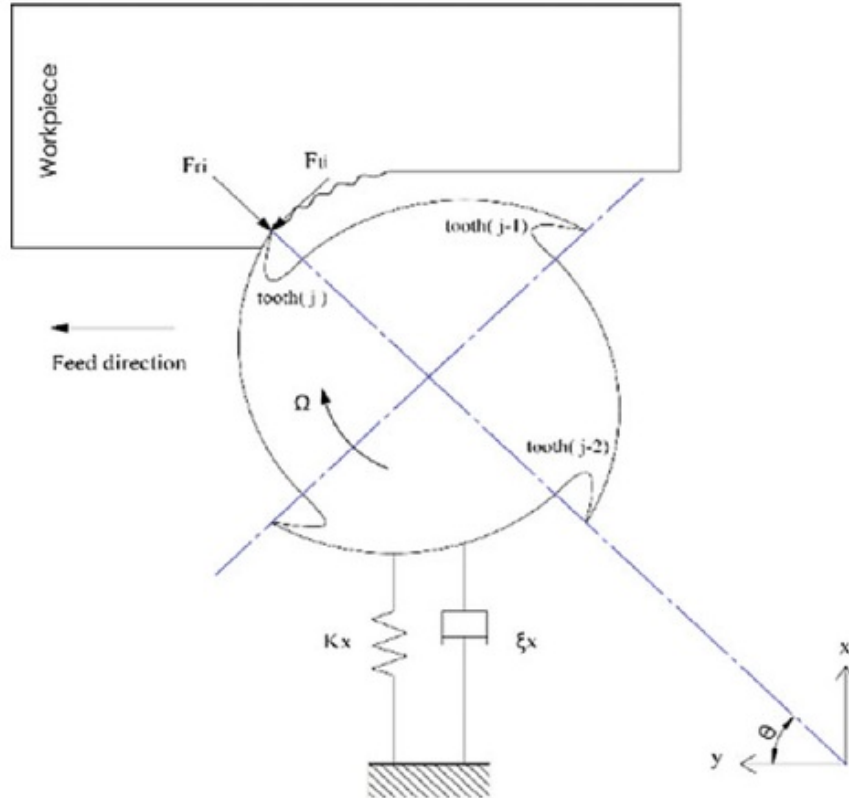
186 The dynamic equations for the tool-workpiece system can be obtained as:

$$187 \quad m_x \ddot{x}_x(t) + \zeta_x \dot{x}_x(t) + k_x x_x = F_x(t) \quad (1)$$

189 where  $m_x$ ,  $\zeta_x$ , and  $k_x$  are the modal mass, damping, and stiffness of the  
190 tool-workpiece system in the X-direction.  $F_x(t)$  is the cutting force in the x-direction.  
191  $\ddot{x}(t)$ ,  $\dot{x}(t)$  and  $x(t)$  are the vibrational acceleration, vibrational speed, and vibrational  
192 displacement of the tool-workpiece system, respectively.

194 The equation of free vibrations for the system by neglecting the damping and the  
195 external force can be written as Eq. (2) [24].





36  
**Fig. 1** Dynamic model of the thin-walled workpiece-tool system

$$M\ddot{x}(t) + Kx(t) = 0 \quad (2)$$

196  
 198 **1**  
 199 where  $M$  and  $K$  are the system mass, and stiffness matrices of size  $(n \times n)$ ,  
 200 respectively, and  $x$  is the  $n$ -dimensional column vector of generalised coordinates.  
 201 Equation (1) for a single degree-of-freedom (SDOF) system can be written as  
 202 Eq. (3).

$$m\ddot{x}(t) + kx(t) = 0 \quad (3)$$

205  
 206 If  $x(t) = x_0 \sin(\omega t)$ , where  $\omega = 2\pi f$  is the rotational frequency, then Eq. (3)  
 207 becomes  $(-\omega^2 m + k)x_0 = 0$ . The solution of  $(-\omega^2 m + k) = 0$  gives the natural  
 208 frequency of the SDOF systems ( $f_n$ ), as shown Eq. (4).

$$f_n = \frac{\omega_n}{2\pi} = \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}} \quad (4)$$

211  
 212 Similarly, Eq. (2) can also be written as

$$(-\omega^2 M + K)x_0 = 0 \quad (5)$$



Or could be written as

$$(K - \lambda M) = 0 \quad (6)$$

Equation (6) represents the equation of the eigenvalues and eigenvectors, where  $\lambda = \omega^2$  are a set of the eigenvalues, the  $\lambda = [\lambda_1, \lambda_2, \dots, \lambda_n]$ , and the corresponding eigenvector matrices are  $\varphi = [\varphi_1, \varphi_2, \dots, \varphi_n]$  or called normal mode.

To identify the frequency content of milling force signals, Fourier transform is commonly used to transform from the time domain to the frequency domain. Since the signals from sensors are discrete, discrete Fourier transform (DFT) usually is used. DFT is given by [14, 25, 26].

$$F(k) = \sum_{n=0}^{N-1} F(n) \exp\left[\left(\frac{-j2\pi}{N}\right)kn\right], 0 \leq k \leq N-1 \quad (7)$$

Based on the periodicity, symmetry, reducibility, and orthogonal of the exponential part of Eq. (7), FFT reduces the computational complexity of an  $N$ -point DFT to about  $N \log_2 N$  arithmetic operations.

$$SF = \frac{n}{60} = \frac{1000v}{60\pi D} \quad (8)$$

[[[The frequency spectrum is discrete to periodic signals; the amplitude spectrum appears at its variation frequency and harmonics. In milling process, the signal of cutting force is periodic, and its variation frequency is tooth passing frequency (TPF), so the amplitude spectrum of the cutting force shows peaks at TPF and its harmonics. However, the peak value of milling force will usually appear at spindle frequency (SF) and its harmonics for the mill run out. SF and TPF are defined as

$$TPF = N.SF = \frac{1000Nv}{60\pi D} \quad (9)$$

where  $n$  and  $v$  are the spindle speed (in revolutions per minute) and linear speed (in metres per minute), respectively, and  $D$  is the diameter of the mill. On TPF, the appearance of peaks at additional frequencies indicates the chatter. This well-known property of milling dynamics is often exploited for the detection of the chatter.]]]

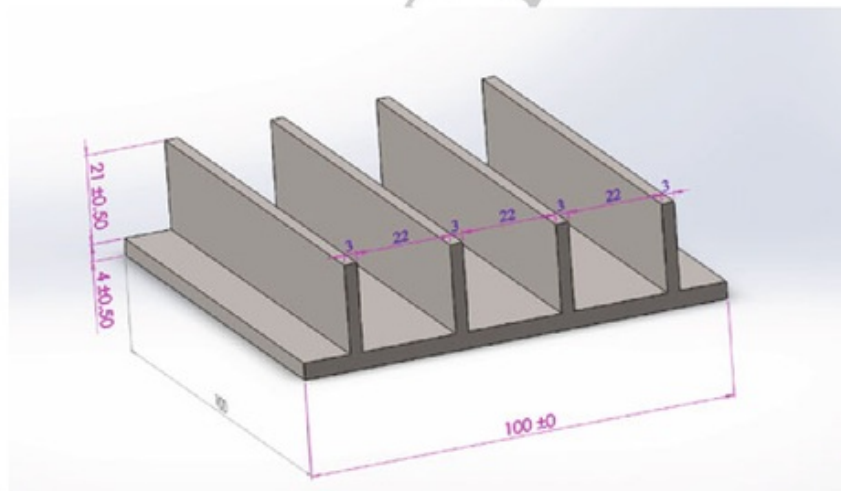
## 2 Experimental Work

The cutting test was carried out on a high-speed milling centre MAHO DMC 835 V CNC 3-axis VMC, with an 18,000 maximum rpm spindle. Experiment set-up is shown in Fig. 2. The end mill tools used AlCrN-coated solid carbide with four cutting edges, the diameter of 10 mm and overhang length of tools is 30 mm.





**Fig. 2** Experimental set-up



**Fig. 3** Geometry and dimension (mm) of the workpiece thin-walled Ti6Al4V

254 The workpiece material was thin-wall titanium alloy Ti6Al4V (grade-5). Figure 3  
255 shows the geometry and dimension of the thin-walled Ti6Al4V workpiece. The  
256 machining was done under MQL-cutting condition using coconut oils as the cutting  
257 fluids. The vibration <sup>43</sup> the workpiece was measured in the three directions of the  
258 tool feed ( $x$ -axis), perpendicular to the machined surface ( $y$ -axis) and the axial  
259 direction of the tool ( $z$ -axis). The workpiece vibration signal was monitored using  
260 accelerometer mounted on 35 mm in near the workpiece. The sampling rate in this  
261 experiment was set 20,000 s. The vibration signals magnified using a Daqcard



**Table 1** Cutting process parameters

Trial numbers	Cutting speed (m/min)	Feed/tooth (mm/tooth)	Spindle frequency (Hz)	Radial DOC (mm)	Axial DOC (mm)
1.	64	0.063	135.76	0.32	7.07
2.	156.25	0.063	31.44	0.32	7.07
3.	100	0.025	212.12	0.32	7.07
4.	100	0.158	212.12	0.32	7.07
5.	100	0.063	212.12	0.32	7.07
6.	100	0.063	212.12	0.32	7.07
7.	100	0.063	212.12	0.32	7.07
8.	100	0.063	212.12	0.32	7.07
9.	100	0.063	212.12	0.32	7.07
10.	100	0.063	212.12	0.32	7.07

262 direct amplifier, and the analogue device was a National Instrument MX and col-  
263 lected by a data collection of the Dewesoft 7.0.6 software. The signals were  
264 analysed by MATLAB R2012a® software. To capture the surface quality, the  
265 Olympus STM6-LM was used. The thin wall was down milled with cutting process  
266 parameters are listed in Table 1.

### 267 3 Results and Discussion

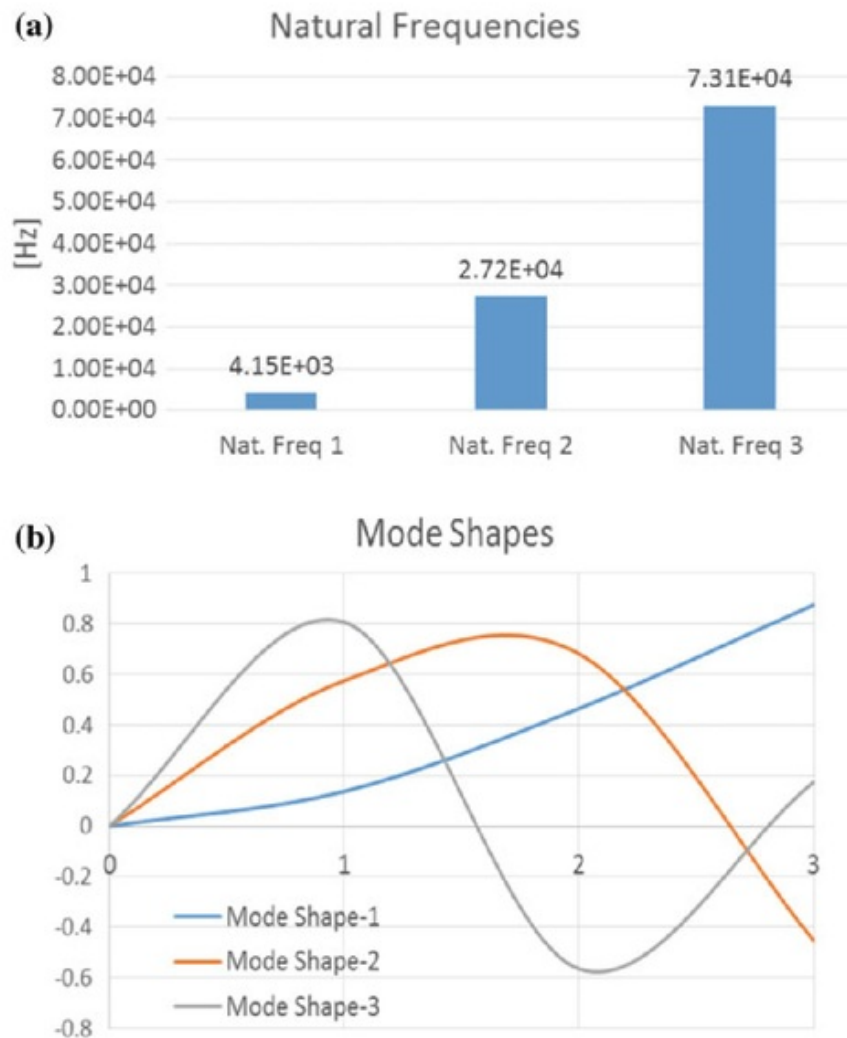
#### 268 3.1 Computation of Thin-Wall Natural Frequency 269 and Vibration Analysis

270 The computation of thin-wall natural frequency is based on free vibrations with  
271 neglecting the damping. Natural frequency values are to compare with tooth  
272 passing frequency values of spindle speed in cutting parameters; it is done to avoid  
273 resonance or chatter in the machining process. The distribution of natural fre-  
274 quencies and mode shapes for SDOF is shown in Fig. 4. Based on Fig. 4 and  
275 Table 1, the frequencies of cutting parameters do not coincide with the natural  
276 frequency.

277 The mean values of workpiece acceleration at different cutting processes are  
278 shown in Fig. 5, in which  $x$ ,  $y$ , and  $z$  represent the mean acceleration of  $x$ -direction,  
279  $y$ -direction, and  $z$ -direction. It is observed that the increase in cutting speed and feed  
280 rate tends to increase acceleration in all the three directions. The acceleration value  
281 in  $y$ -direction or perpendicular to the machined surface is higher than the other  
282 directions.

283 The frequency and surface topography will be used to analyse further vibration  
284 analysis on thin wall. Figure 6 section first (time domain vs. acceleration) is shown



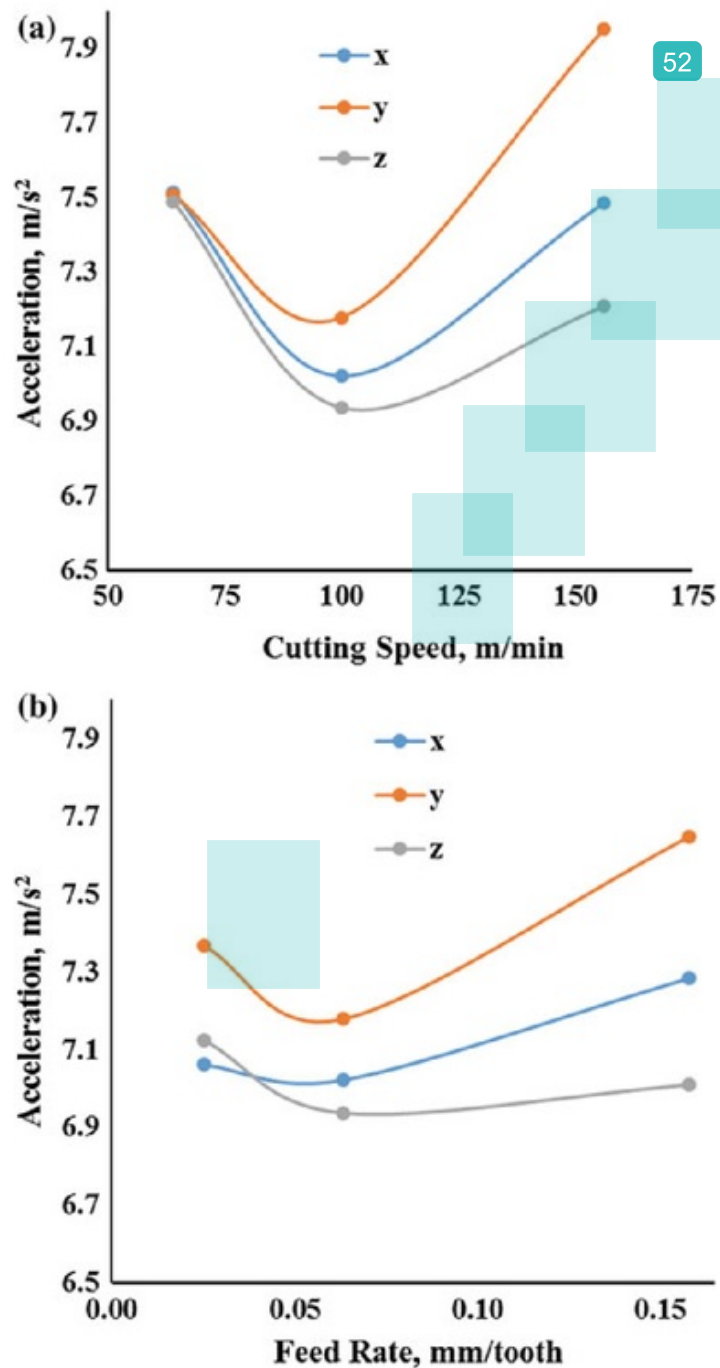


**Fig. 4** a Natural frequency. b Mode shapes of the thin wall

285 the raw signals of the vibration. The cutting process is divided into three states—  
286 entry cutting, machining cutting, and exit cutting. The data during machining state  
287 is used to analyse the influences cutting process towards vibration. To verify the  
288 cutting process, whether unstable machining (chatters) occur, the vibration y-  
289 direction was analysed using FFT. The fast fourier transform spectrum is shown in  
290 Fig. 6.

291 It is shown that the peak values of milling vibration are more significant when  
292 the cutting speeds are 156.25 m/min, feed rate 0.025 and 0.158 mm/tooth. When  
293 cutting speed is 100 m/min, its frequency spectra distribution is stable. In order to  
294 further analyse stability machining (chatter), no chatter appears on all machining.  
295 Dominant vibration or maximum point's peak value occurs at 4000, 4503, 5333,  
296 and 6000 Hz, but it causes no chatter.

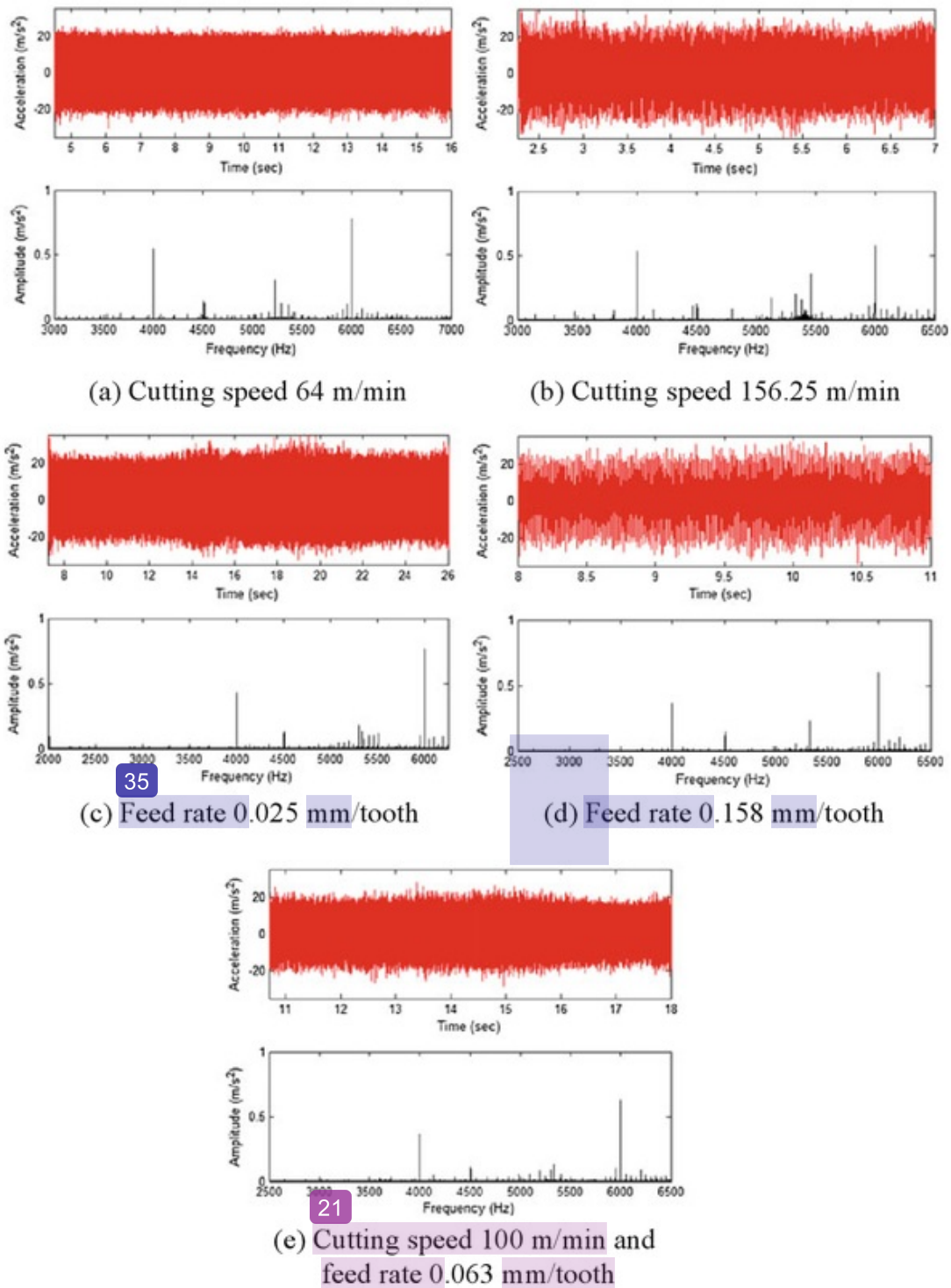
**Fig. 5** Vibration acceleration on, **a** cutting speed, **b** feed rate variation



### 3.2 Surface Quality

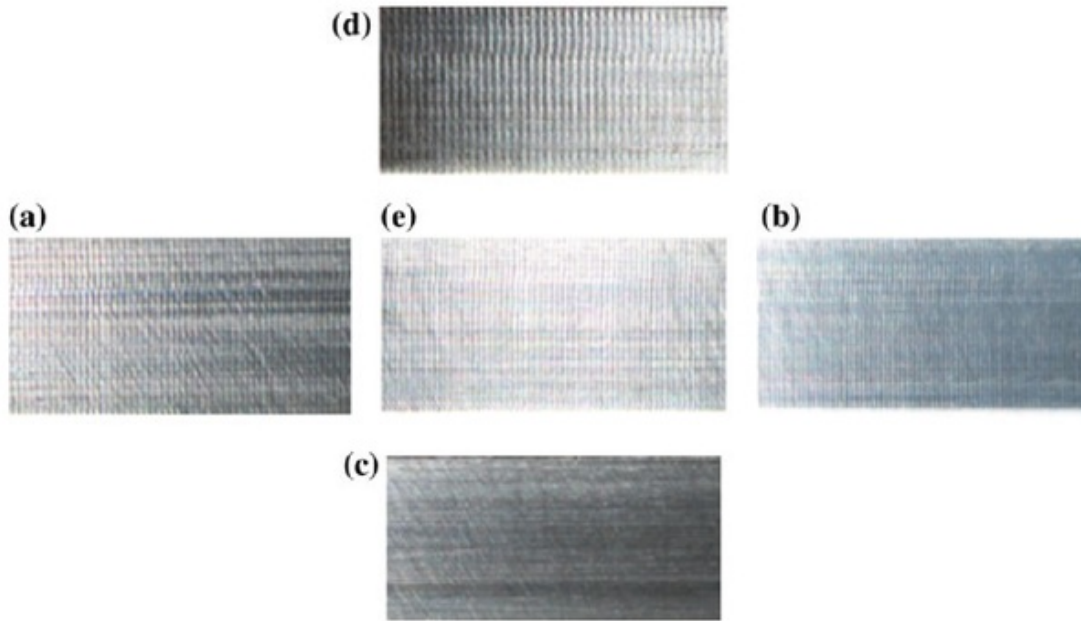
However, on the surface topography as shown in Fig. 7, the surface is poorer at a maximum cutting speed and maximum feed rate. Based on these results, it can be proven that the experiments were in good agreement and the maximum vibration appears far away from the natural frequency.





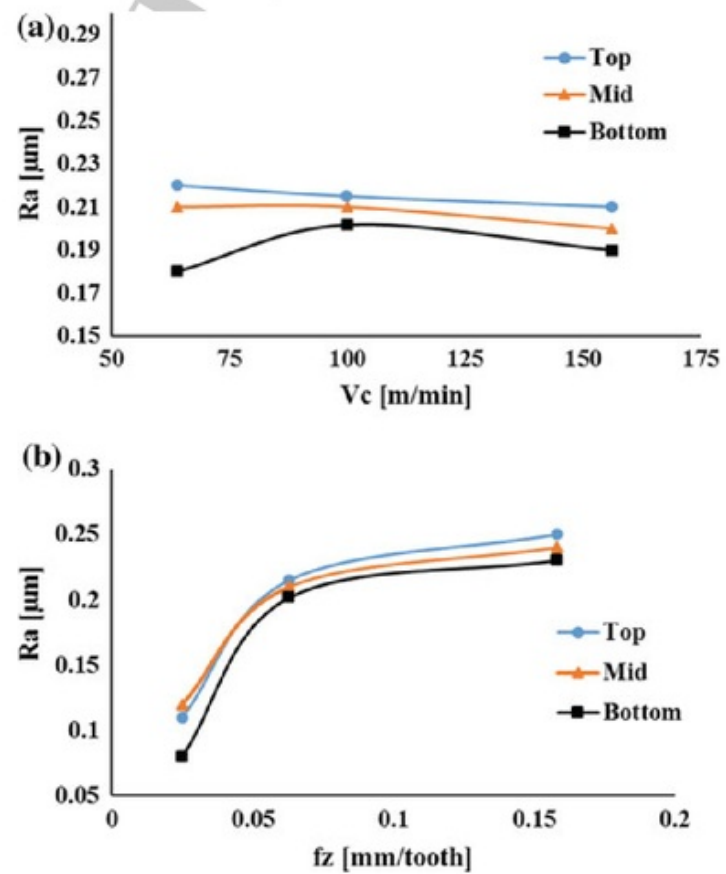
**Fig. 6** Time domain and FFT output during machining at cutting speed and feed rate variation

302 The surface topography has shown small influence due to vibration on the  
303 surface texture. This phenomenon can be proven when the surface roughness values  
304 are measured using surface roughness tester Accretech Handy-Surf type E35A/E.  
305 The influence of cutting speed and feed rate is shown in Fig. 8a, b.



**Fig. 7** Surface photographs of the workpiece at cutting speed and feed rate variations: **a**  $V_c = 64$  m/min, **b**  $V_c = 156.25$  m/min, **c**  $f_z = 0.025$  mm/tooth, **d**  $f_z = 0.158$  mm/tooth, **e**  $V_c = 100$  m/min and  $f_z = 0.063$  mm/tooth

**Fig. 8** Influence of cutting speed, **a** and feed rate, **b** on surface quality at several positions of thin-wall Ti6Al4V





306 From Fig. 8a, it is apparent that increasing cutting speed generally affected on  
307 decreasing surface roughness values, hence yield in better surface quality. On the  
308 other hand, increasing the feed rate yields in poorer surface quality as shown in  
309 Fig. 8b.

310 This phenomenon is agreeing with the basic theory propagation of surface  
311 roughness, which also proven in [27] during hard turning on AISI D2 steel. Solely  
312 at the bottom of the thin wall, the surface roughness is increased with the rise of  
313 cutting speed. From Fig. 8, it is also to recognise that the surface roughness values  
314 decrease from the top to the bottom of the thin wall. This could be caused by the  
315 deflection on the top of the thin wall is higher than the bottom. Thus, the surface  
316 deterioration is more influenced on the top of the thin wall.

## 317 4 Membrane Technology

### 318 4.1 Potential and Handling of Membrane Technology

319 It is known that conventional cutting fluid is hazardous, but reducing the amount of  
320 cutting fluid to control environmental hazard leads to compromising performance  
321 measures. In this case, operations with minimum quantity lubrication (MQL) is one  
322 of the strategies that can offer technological that associated environmental concerns  
323 and economic advantages over the traditional fluid application. Under MQL,  
324 microdroplets of sustainable lubricants are supplied in the machining zone. The  
325 prevailing trend of many researchers in machining processes, vegetable oil, has  
326 been selected as cutting fluid based on their ability to influence performance and  
327 characteristics such as biodegradability, oxidation stability, and storage stability.

328 Vegetable oils possess excellent lubrication properties, resistance to corrosion,  
329 and high flash and boiling points.

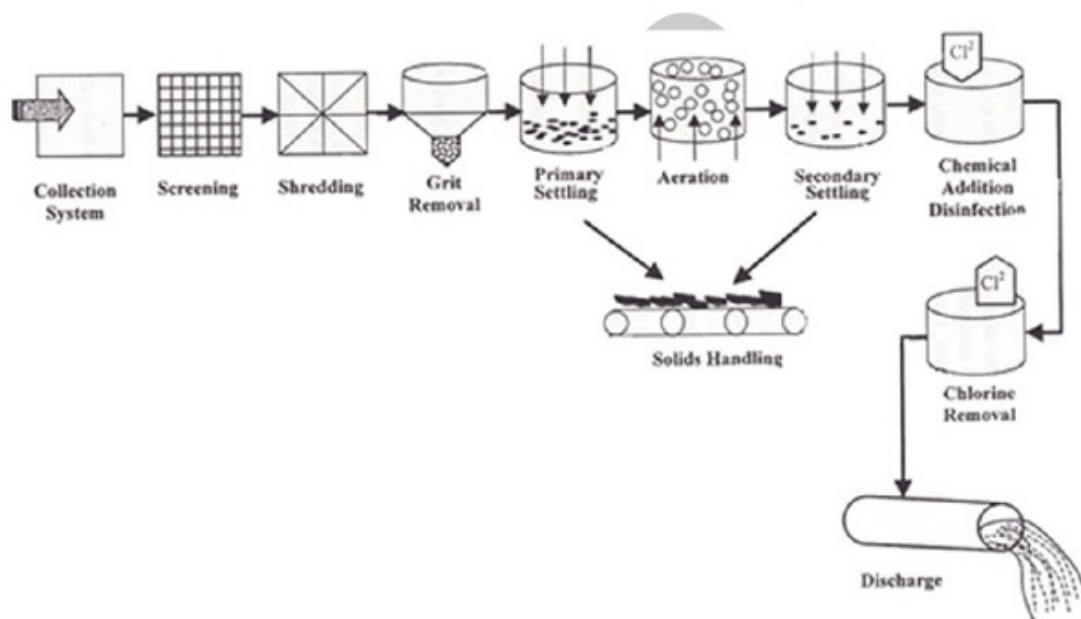
330 Storage and disposal of exhausted cutting fluid have always been challenging for  
331 the machining industry.

332 Removing the chips in the wasted cutting fluid is the first step to treat the waste  
333 cutting fluid [28]. In this study, oily water emulsion, similar as wasted cutting fluid,  
334 are the primary pollutants emitted into the water by manufacture operation and tend  
335 to have significant pollution problem because oilfield produced water has distinc-  
336 tive characteristics due to organic and inorganic matter. Fatty alcohols and synthetic  
337 hydrocarbons which include the waste cutting fluid are initiated hazardous materials.  
338 Some treatments of oily wastewater have been studied namely, chemical  
339 emulsification, pH, gravity settling, centrifugal settling, filtration, coalescence, heating  
340 treatment, electrostatic coalescence, and membrane filtration. The unit operations and  
341 processes used for the removal of significant constituents found in wastewater are  
342 tabulated in Table 2.

31

**Table 2** Unit operations and processes used to removed constituents found in wastewater

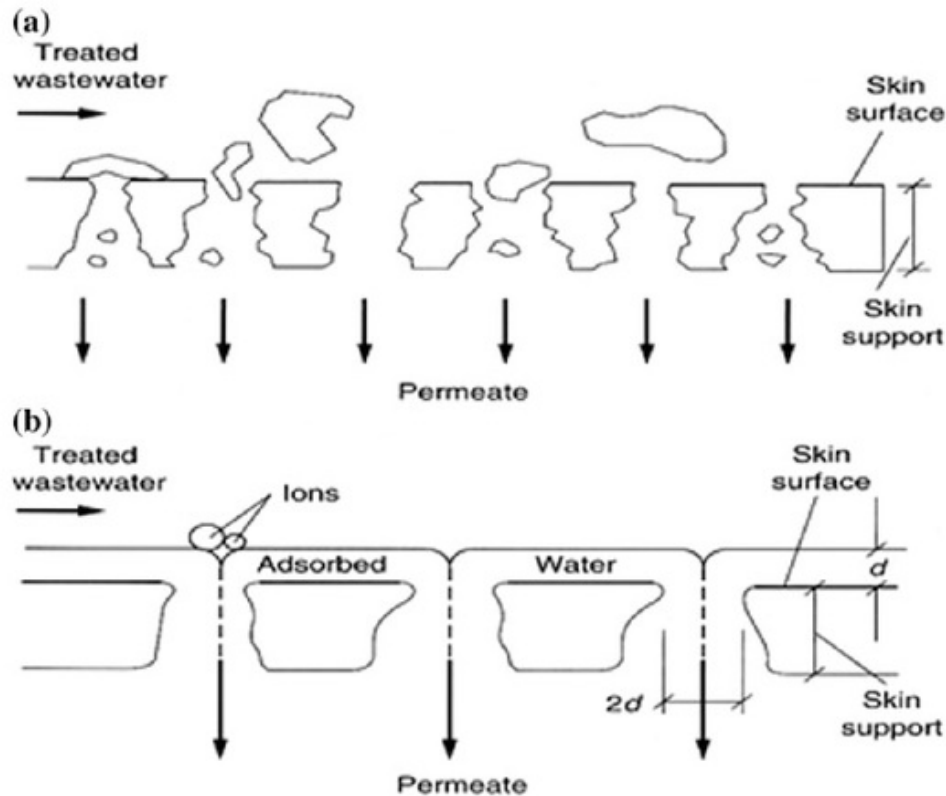
Constituents	Appropriate treatment technologies
Suspended solids	Screening, grit removal, sedimentation, flotation, chemical precipitation, surface filtration
Biodegradable organics	Aerobic suspended growth variations, Aerobic attached growth variations, physical–chemical systems, chemical oxidation, advanced oxidation, membrane filtration
Refractory organics	Carbon adsorption, chemical oxidation, ion exchange, breakpoint chlorination, membrane filtration
Heavy metals	Membrane filtration, evaporation, electrodialysis, chemical precipitation, ion exchange
Fat, oil, and grease	Coagulation/flocculation/flotation, membrane ultrafiltration
Colloidal and dissolved solids	Membrane filtration, chemical treatment, carbon adsorption, ion exchange

**Fig. 9** Mechanism of wastewater treatment

343 The suspended solids and other constituents that are difficult to remove are being  
344 treated by improved and new technologies. The unit operation for wastewater  
345 treatment is shown in Fig. 9, while the terminology of wastewater constituent  
346 removal using a membrane is shown in Fig. 10.

347 The performance evaluation of various membrane materials was reported by  
348 [29]. They evaluated the suitable membrane materials for the coolant wastewater  
349 treatment and the effect of nanoparticles additives on the membrane morphology.

350 They concluded that the application of PVDF membrane in the metal industry  
351 for long-term performance could be an alternative solution regarding the purpose of  
352 nanoparticles in the membrane to minimise fouling and prolong the membrane



**Fig. 10** Rejection of ions by adsorbed water layer in waste water treatment by membrane technology

353 lifetime that affects directly to the enhancement of the efficiency of the treatment  
354 process. Heterogeneity of coolant effluent has been reported by some researchers  
355 because it is made by nature and effect of fouling that was harder to control and  
356 forecast. The fouling phenomenon of the membrane is one of the drawbacks in  
357 membrane technology that cannot be prevented but can be minimised. Related to  
358 the fouling phenomenon, hydrophilicity characteristics plays also important role in  
359 oily wastewater filtration. Hydrophilicity contributes to the formation of a thin,  
360 protective water film on the membrane surface that increases the water removal  
361 from wastewater cutting fluid. On the otherhand, hydrophobicity tends to repel and  
362 not absorb water. It has been reported that hydrophilicity membranes have more  
363 advantages concerning fouling than hydrophobic membranes [29].

#### 364 **4.2 PVDF Membrane for Mitigation of Wasted** 365 **Cutting Fluids**

366 As known, membrane separations have been significantly developed over the last  
367 three decades and are becoming an essential place in wastewater treatment.  
368 The membrane technology has emerged as an alternative to the conventional





369 physical–chemical treatment process and also decreased the environmental pollu-  
370 tion significantly. Membrane filtration system involves the passage a wastewater  
371 through the thin membrane for removing particulate materials, organic matters,  
372 nutrients, and dissolved substances, which cannot be removed by conventional  
373 treat<sup>41</sup> processes. Membrane processes include microfiltration (MF), ultrafiltra-  
374 tion (UF), nanofiltration (NF), reverse osmosis (RO), and electro dialysis (ED). The  
375 microfiltration and ultrafiltration membranes are used for filtrating the secondary  
376 effluent in depth and surface filtration. Meanwhile, nanofiltration, reverse osmosis,  
377 <sup>13</sup> electro dialysis systems are used for removing the dissolved solids. They also  
378 have high oil removal effi<sup>2</sup>ency, low energy cost and compact design compared  
379 with traditional treatment. Many studies of membrane separation for oily wastew-  
380 ater treatment have been reported, particularly in microfiltration (MF) and ultra-  
381 filtration (UF). The performance of hydrophobic polyvinylidene fluoride for oily  
382 wastewater filtration can be characterised according to their permeability, re<sup>9</sup>jection  
383 ability, and fouling resistance [30]. More specifically, such performance can be  
384 compromised due to pore clogging via oil particle, preferential adsorption of oil  
385 which can result in fouling as well as the formation of cake layers on the membrane  
386 surface.

387 Regarding the application of membrane in wasted cutting fluids treatment,  
388 PVDF membrane achieved the significant result to remove the contaminant and also  
389 remove the colour comp<sup>3</sup>onent. Part of colour pigment which affected by vaporisa-  
390 tion could be remained by adsorption on suitable bleaching earth. The remaining  
391 colour components are the thermally degraded during deodorisation at high  
392 tem<sup>3</sup>perature (150 °C) for 100 min.

393 Part of the colour pigments are physically adsorbed by bleaching earth, and other  
394 components are chemically bound to bleaching clay via covalent or ionic bonds  
395 [31]. Decomposes peroxide in <sup>3</sup>oxoyl and alkyl radicals occur as first step in  
396 oxidation pathway. Second step, acid activation enhances <sup>12</sup> adsorptive power due  
397 to an increasing negative surface area of the membrane. Based on these results, it  
398 can be concluded that modified PVDF membrane with the negative charged surface  
399 is the better solution in order to treat the wasted cutting fluid.

### 400 4.3 Experimental Set-up of PVDF Membrane Technology

401 The coolant wastewater was produced while the milling of thin-wall Ti6Al4V using  
402 coconut oils as cutting fluids under MQL systems. After finished the experiment,  
403 the exhausted cutting fluid was collected in a bottle. For this experimental purpose,  
404 it is must to prepare a synthetic coolant wastewater according to a collected sample  
405 of MQL-exhausted cutting fluids, which was collected in the previous experiments.  
406 The prepared synthetic coolant wastewater is to be used as the feed solution in  
407 ultrafiltration experiments [32].



**Table 3** Properties of PVDF membrane

Parameter of the membrane	Type/value
Membrane material	PVDF/SiO <sub>2</sub>
Membrane configuration	Hollow fibre
Inner diameter (mm)	0.6
Outer diameter (mm)	1.2
Membrane area (dm <sup>2</sup> )	10.48
Pore size (nm)	35.2

408 The submerged membrane separation system used in this experiment consists of  
409 a feed reservoir up to 14 l volume, hollow fibre bundles, a peristaltic pump, a  
410 permeate flow metre, and a permeate collector. The boundary conditions of the  
411 filtration experiments are as follows: vacuum on the permeate side 0.5 bar abs,  
412 room temperature.

413 The membrane was produced using a peristaltic pump (Master flex model 7553–  
414 79, Cole Palmer) with the water permeate being withdrawn from the open end of  
415 fibres. In order to let the water permeate from outside to the inside of the hollow  
416 fibre, the transmembrane pressure (TMP) was maintained at a constant pressure of  
417 0.5 bar. The turbulent flow was created using the continuous aeration so that the  
418 cake layer thickness and the average particle size could be reduced.

419 The properties of the membrane used in this experiments are given in Table 3.

420 In these experiments, the hollow fibre membranes were immersed in the feed  
421 reservoir. The withdrawal of permeate through the fibre was generated using the  
422 employment of vacuum on the outlet of the fibre lumen [33–35].

423 To characterise the oily machining wastewater, several substances were taken  
424 into account as measured parameters, namely oil and grease, chemical oxygen  
425 demand (COD), total organic carbon (TOC), sulphide, and total suspended solids  
426 [36].

#### 427 **4.4 PVDF Membrane Experiments Results**

428 The removal of organic wastes from oily wastewater has been proven successfully  
429 using developed PVDF membrane technology and its application in coolant  
430 wastewater filtration. In this device, hollow fibre membranes are directly immersed  
431 in the feed reservoir with the withdrawal of permeate through the fibres in vacuum  
432 pressure application on the fibre lumen outlet of the membrane. As known, coolant  
433 wastewater was characterised by the presence of chemical oxygen demand (COD),  
434 total organic carbon (TOC), and suspended solids (TSS). After coolant wastewater  
435 filtrating using PVDF hollow fibre membrane with factors such as mixed liquor  
436 suspended solids, the concentration of coolant wastewater, pH and hydraulic  
437 retention time <sup>23</sup> the results of the study were achieved in the value of COD 555 mg/L,  
438 TOC of 29.1 mg/L, and suspended solids of 20 mg/L. These values were achieved





439 entirely using modified PVDF hollow fibre membrane with SiO<sub>2</sub> additives that  
440 affected as modifier area, highly miscible, fine suspend ability in aqueous solution  
441 and relatively environmentally inert. PVDF/SiO<sub>2</sub> has been found to be a promising  
442 modifier to improve the permeability and selectivity of PVDF membrane [32].

## 443 5 Conclusions and Future Directions

444 In this study, dynamic behaviour during end milling thin wall of Ti6Al4V is ver-  
445 ified. The results found are as follows:

- 446 1. It was found that the natural frequencies occurred are 4154.5, 27,203,  
447 73,089 Hz for the first, second, and the third, respectively.
- 448 2. The dominant vibration or maximum point's peak value occurs at 4000, 4503  
449 and 5333, and 6000 Hz.
- 450 3. The vibration value in y-direction or perpendicular to the machined surface is  
451 higher than the x-direction and z-direction.
- 452 4. The value of acceleration in three directions increased significantly with the  
453 increase of cutting speed and feed rate.
- 454 5. The surface quality is better when the cutting speed increased. In contrary, the  
455 surface quality becomes worst when the feed rate rise.
- 456 6. The results of the study were achieved in the value of COD 555 mg/L, TOC of  
457 29.1 mg/L, and suspended solids of 20 mg/L. These values were achieved  
458 entirely using modified PVDF hollow fibre membrane with SiO<sub>2</sub>.
- 459 7. PVDF/SiO<sub>2</sub> has been found to be a promising modifier to improve the perme-  
460 ability and selectivity of PVDF membrane.

462 The proposed future work in this field is to observe the opportunity of combining  
463 vegetable oils in MQL, cryogenic, and air-cooled systems.

464 In order to mitigate the hazardous effect of the wasted cutting fluids, the PVDF  
465 membrane offers an excellent solution. Thus, the green machining through coconut  
466 oils as cutting fluids in MQL system has been proven the optimum cutting condition  
467 for the aerospace materials such as titanium alloy.

468 Through the optimum selection of a cutting condition, the occurred vibration in  
469 machining of Ti6Al4V can be controlled in the acceptable zone. Thus resulted in  
470 adequate surface quality.

471 The higher cutting speed should be investigated in the future to find higher  
472 optimum cutting condition, which suitable the machining of titanium

473 In the handling of wasted cutting fluids, it is essential to explore the opportunity  
474 of other types of the membrane in filtering the wasted cutting fluids to foster the  
475 environmentally friendly machining process, especially for aerospace materials.





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